

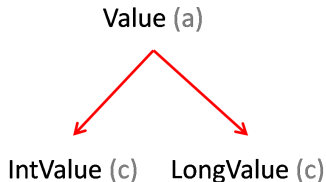
Decision Procedure for Partial Orders

Elena Sherman

September 12, 2009

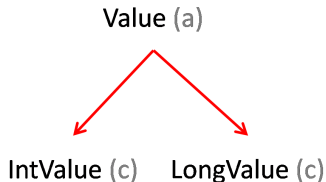
Subtyping in Kiasan

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Value convert(Value v) {
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2: if (v instanceof IntValue) {
3:     result = ((IntValue)v).value;
   } else {
4:     result = ((LongValue)v).value;
   }
5: return new LongValue(result);
}
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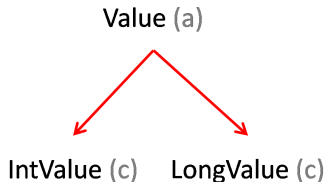
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- DP = modeling of subtyping as an uninterpreted function → weak modeling → lots of false positives.

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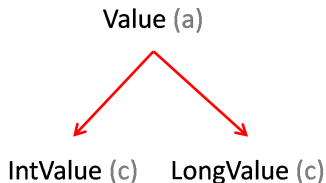


- DP = modeling of subtyping as an uninterpreted function → weak modeling → lots of false positives.
- Optimization: type is refined to the lowest successfully casted subclass → avoiding some calls to DP → few false positives.

Example of Subtyping in Kiasan

```
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8: }
```

❶ TypeOf(v) = Value

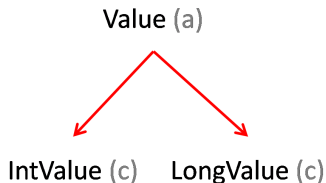


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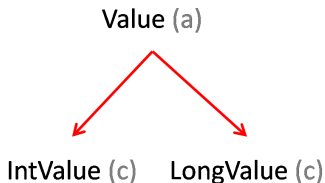
❶ TypeOf(v) = Value, TypeOf(v) = IntValue



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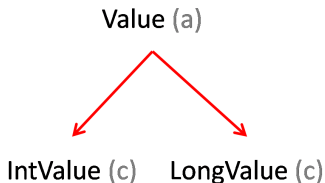
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- 1 TypeOf(v) = Value, TypeOf(v) = IntValue, casting OK

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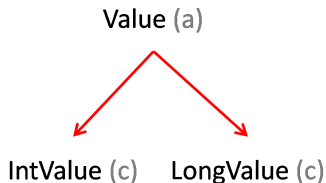
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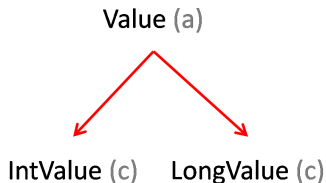


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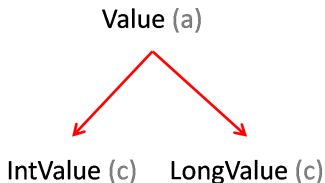


- ❶ TypeOf(v) = Value, TypeOf(v) = IntValue, casting OK
- ❷ TypeOf(v) = Value, TypeOf(v) = Value

Example of Subtyping in Kiasan

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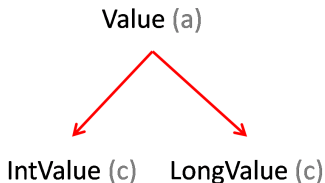
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- ② TypeOf(v) = Value, TypeOf(v) = Value, casting **EXCEPTION**

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- ② TypeOf(v) = Value, TypeOf(v) = Value, casting **EXCEPTION**

Trace 2 produces false positive → need better DP → DP-PO.

Theory of Partial Order (PO)

- 1 Variables: a set of variables X .
- 2 Logical symbols: $\{\wedge, \neg\}$.
- 3 Nonlogical symbols: $\{<:, E\}$, where E is the set of poset elements (constants) and $<:$ is defined as :
 - 1 Reflexive: $e <: e$ where $e \in E$
 - 2 Antisymmetric : $e_1 <: e_2$ and $e_2 <: e_1 \rightarrow e_1 = e_2$ where $e_1, e_2 \in E$.
 - 3 Transitive: $e_1 <: e_2$ and $e_2 <: e_3 \rightarrow e_1 <: e_3$ where $e_1, e_2, e_3 \in E$.
- 4 Syntax:

formula : *formula* \wedge *formula* | *atom* | \neg *atom*

atom : $x <: e$ | $e <: x$ | $e_1 <: e_2$

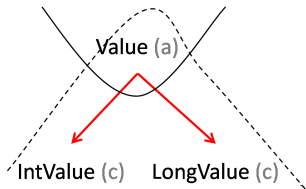
where $x \in X$ and $e, e_1, e_2 \in E$.

Example of Subtyping using DP-PO

```

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❶ $v <: \text{Value}, \neg(\text{Value} <: v) \rightarrow \text{SAT}$

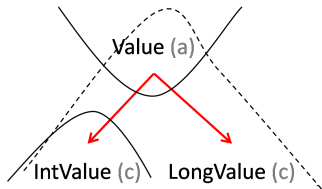


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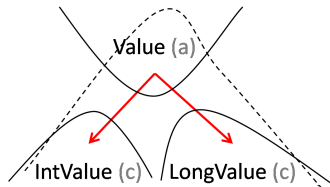


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- ❷ $\neg(v <: \text{IntValue}) \rightarrow \text{SAT}$
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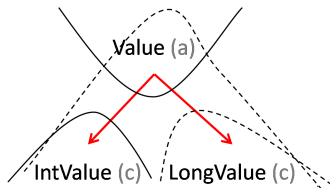


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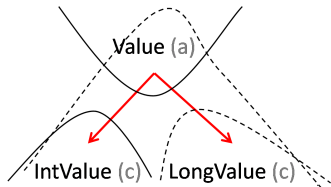
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The false positive exception is eliminated.



Design

- No $x_1 <: x_2$ constraint type \Rightarrow variables are independent.
- Preserve clarity.
- Keep only necessary information for each variable.



- Each variable x_i has its own set of elements satisfying constraints associated with x_i .
- Create separate sets of elements for each of 4 constraint types:
 $x <: e$, $e <: x$, $\neg (x <: e)$, $\neg (e <: x)$.
- Keep only “front line” poset elements in a corresponding constraint type set - take advantage of the transitivity property.

sup Set

sup

$$\begin{aligned} \text{sup}(x) = \{ & e | \forall e_c, \forall e_d \in D(e) : e_d <: e_c \\ & \wedge \exists e_c, \forall e_a \in A(e) \setminus e : e_a \not<: e_c \} \end{aligned}$$

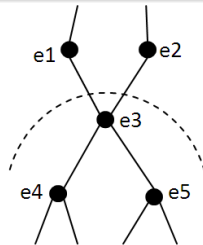
where e_c is a poset element in a $x <: e_c$ constraint, $D(e)$ - descendants of e and $A(e)$ - ancestors of e (include itself).

Suppose we have:

$x <: e_1, x <: e_2, x <: e_3,$

so that $e_c \in \{e_1, e_2, e_3\}$

$$\Rightarrow \text{sup}(x) = \{e_3\}$$



sup_not Set

sup_not

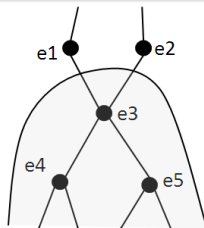
$$\begin{aligned} \text{sup_not}(x) = \{ & e \mid \forall e_c, \forall e_a \in A(e) : \neg(e_a <: e_c) \\ & \wedge \exists e_c, \forall e_d \in D(e) : \neg(e_d \not<: e_c) \} \end{aligned}$$

where e_c is a poset element in a $\neg(x <: e_c)$ constraint.

Suppose we have:

$\neg(x <: e_3), \neg(x <: e_4),$
 so that $e_c \in \{e_3, e_4\}$

$$\Rightarrow \text{sup_not}(x) = \{e_3\}$$



sub Set

sub

$$sub(x) = \{e | \forall e_c, \forall e_a \in A(e) : e_c <: e_a \wedge \exists e_c, \forall e_d \in D(e) \setminus e : e_d \not<: e_c\}$$

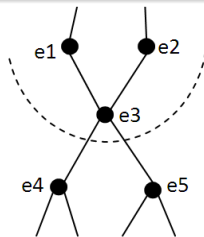
where e_c is a poset element in a $e_c <: x$ constraint.

Suppose previously we have:

$e_4 <: x, e_5 <: x, e_3 <: x,$

so that $e_c \in \{e_3, e_4, e_5\}$

$$\Rightarrow sub(x) = \{e_3\}$$



sub_not Set

sub_not

$$\begin{aligned} \text{sub_not}(x) = & \{e \mid \forall e_c, \forall e_d \in D(e) \setminus e : \neg(e_c <: e_d)\} \\ & \wedge \exists e_c, \forall e_a \in A(e) : \neg(e_c \not<: e_a) \end{aligned}$$

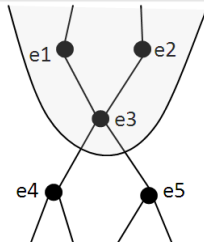
where e_c is a poset element in a $\neg(e_c <: x)$ constraint.

Suppose previously we have:

$\neg(e_1 <: x), \neg(e_3 <: x),$

so that $e_c \in \{e_1, e_3\}$

$\Rightarrow \text{sub_not}(x) = \{e_3\}$



SAT / UNSAT

Using these 4 sets we can determine if a *formula* is SAT or UNSAT:

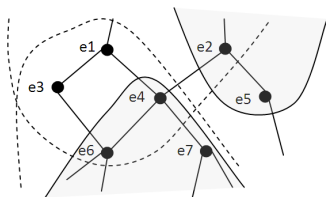
SAT / UNSAT

A *formula* is SAT when $\forall x_i \in X \exists$ a path p from $e_{sup} \in sup(x_i)$ to $e_{sub} \in sub(x_i)$ and $\exists e_p \in p$ such that $e_p \notin D(e_{sup_not}) \wedge e_p \notin A(e_{sub_not})$.

Example

$$\text{formula} = x <: e_1 \wedge \neg(x <: e_4) \wedge e_6 <: x \wedge \neg(e_5 <: x)$$

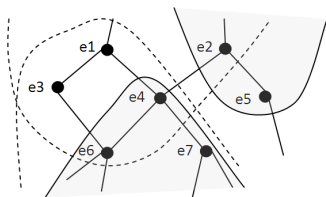
- 1 $x <: e_1 \Rightarrow \text{sup}(x) = e_1$
- 2 $\neg(x <: e_4) \Rightarrow \text{sup_not}(x) = e_4$
- 3 $e_6 <: x \Rightarrow \text{sub}(x) = e_6$
- 4 $\neg(e_5 <: x) \Rightarrow \text{sub_not}(x) = e_5$



Example

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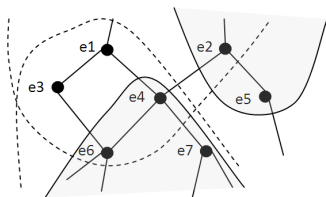
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- Find a path from e_1 to e_6
 $p = (e_1, e_3, e_6)$



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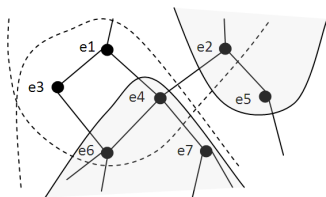
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- Find a path from e_1 to e_6
 $p = (e_1, e_3, e_6)$
 - Is $e_6 \in D(e_4)$?



Example

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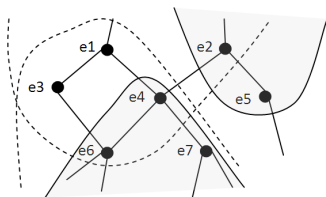
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- Find a path from e_1 to e_6
 $p = (e_1, e_3, e_6)$
 - Is $e_6 \in D(e_4)$? **YES**



Example

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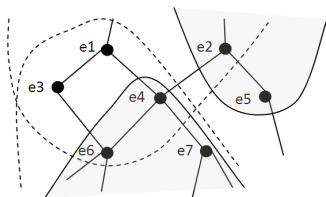
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- Find a path from e_1 to e_6
 $p = (e_1, e_3, e_6)$
 - Is $e_6 \in D(e_4)$? **YES**
 - Is $e_3 \in D(e_4)$?



Example

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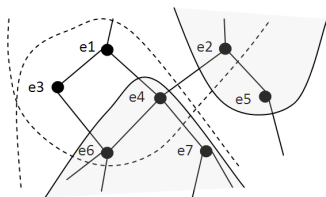
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- Find a path from e_1 to e_6
 $p = (e_1, e_3, e_6)$
 - Is $e_6 \in D(e_4)$? **YES**
 - Is $e_3 \in D(e_4)$? **NO**



Example

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- Find a path from e_1 to e_6
 $p = (e_1, e_3, e_6)$
 - Is $e_6 \in D(e_4)$? **YES**
 - Is $e_3 \in D(e_4)$? **NO**
 - Is $e_3 \in A(e_5)$? **NO** \rightarrow **SAT**



Future Work

- Better/other incremental reasoning.
- Better data structure for efficient descendant/ascendant querying.
- Considering a fragment for Java type hierarchy.
- Separating special cases, e.g. some of the sets are empty.