

Decidable logics combining heap structures and data

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Outline

Overview

STRAND Logic

Deciding STRAND Fragments

Program Verification using STRAND

Logic and SMT Solvers

- Logic
 - a fundamental technique in program verification and analysis
 - many tools need some form of symbolic reasoning
 - high computational complexity

Logic and SMT Solvers

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 - a fundamental technique in program verification and analysis
 - many tools need some form of symbolic reasoning
 - high computational complexity
- SMT Solvers
 - check satisfiability in particular theories
 - engines of proof that serve many programming verification and analysis techniques

Applications

- Test case generation
- Verifying compilers
- Abstraction
- Invariant generation
- Type checker
- Model based testing

Applications@Microsoft of Z3



HAVOC



Terminator T-2

VCC



NModel

Vigilante

SpecExplorer



F7

SAGE

SMT@Microsoft

Microsoft
Research

Theories Supported by SMT Solvers

- Equality over uninterpreted function and predicate symbols
- Real and integer arithmetic
- Bit-vectors
- Arrays
- Tuple/record/enumeration types and algebraic data-types

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Heap Structure + Data ?
(Example: binary search tree)

Related Work

HAVOC (*Lahiri and Qadeer: POPL'08*)

- reasoning with generic heaps combined with an arbitrary data-logic
- awkward syntax restrictions, to obtain decidability
- efficient, but not expressive, cannot even handle doubly-linked lists

CSL (*Bouajjani et al.: CONCUR'09*)

- similar sort-based syntax restrictions
- generalize to handle doubly-linked list

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Both cannot even handle binary search trees!

Our Contribution

- A new logic, called STRAND
 - defined over a class of recursive data structure \mathcal{R}
 - $\exists \vec{x} \forall \vec{y} \varphi(\vec{x}, \vec{y})$
 - where φ is an Monadic Second Order (MSO) formula combines heap structures and data, but where the data-constraints are **only allowed** to refer to \vec{x} and \vec{y}
 - Example:
 $\forall y_1 \forall y_2. (\exists z. (y_1 \rightarrow z \wedge z \rightarrow y_2) \Rightarrow (data(y_1) \leq data(y_2)))$

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 - semantically defined, but syntactically checkable
 - based on the notion of **satisfiability-preserving embeddings**

Our Contribution

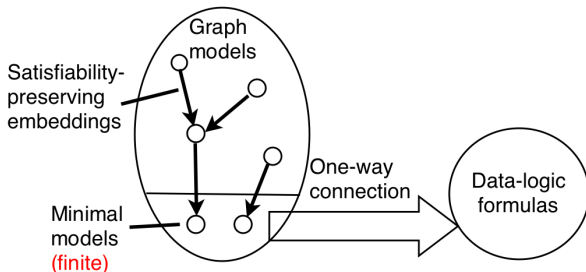
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- On certain classes of recursive data structures, identify a decidable syntactic fragment of STRAND

Combining Theories

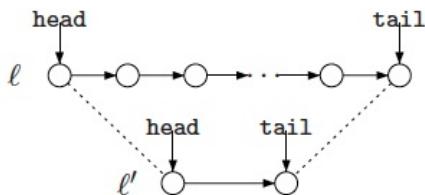
Traditional:

- Nelson-Oppen approach
- two-way connection, quantifier free
- full FOL is undecidable

Our Scheme:



Contract a Sorted List

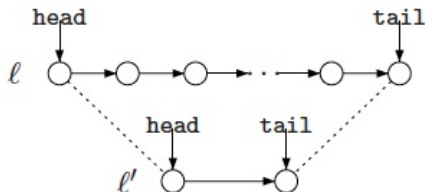


$$\varphi_1 : \quad d(\text{head})=1 \wedge d(\text{tail})=10^6 \wedge \\ \forall y_1 \forall y_2. ((y_1 \rightarrow^* y_2) \Rightarrow d(y_1) \leq d(y_2))$$

$$\widehat{\varphi}_1 : \quad p_1(\text{head}) \wedge p_2(\text{tail}) \wedge \\ \forall y_1 \forall y_2. ((y_1 \rightarrow^* y_2) \Rightarrow p_3(y_1, y_2))$$

(for any y_1, y_2, p_1, p_2, p_3 hold for free!)

One Million Example



$$\varphi_2: \quad d(\text{head})=1 \wedge d(\text{tail})=10^6 \wedge \\ \forall y_1 \forall y_2. ((y_1 \rightarrow y_2) \Rightarrow d(y_2) = d(y_1) + 1))$$

$$\widehat{\varphi}_2: \quad p_1(\text{head}) \wedge p_2(\text{tail}) \wedge \\ \forall y_1 \forall y_2. ((y_1 \rightarrow y_2) \Rightarrow p_3(y_1, y_2)))$$

(When $y_1 = \text{head}$, $y_2 = \text{tail}$, $p_3(\text{head}, \text{tail})$ does not hold for free!)

Outline

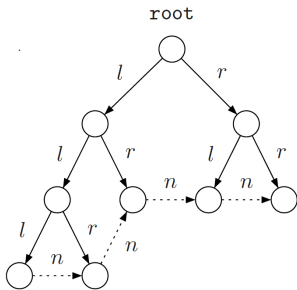
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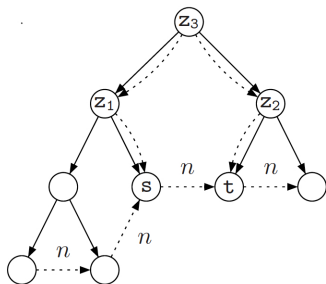
Recursive data-structures



Example

leaves of the tree are connected by a linked list.

Recursive data-structures



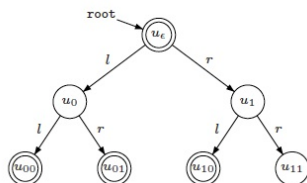
Example

$$E_{next}(s, t) \equiv leaf(s) \wedge leaf(t) \wedge \exists z_1, z_2, z_3 (E_l(z_3, z_1) \wedge E_r(z_3, z_2) \wedge RightMostPath(z_1, s) \wedge LeftMostPath(z_2, t))$$

Syntax of STRAND Logic

\exists DVar	$x \in$	Loc
\forall DVar	$y \in$	Loc
GVar	$z \in$	Loc
Variable	$v ::=$	$x \mid y \mid z$
Set – Variable	$S \in$	2^{Loc}
Constant	$c \in$	$Sig(\mathcal{D})$
Function	$g \in$	$Sig(\mathcal{D})$
\mathcal{D} –Relation	$\gamma \in$	$Sig(\mathcal{D})$
\mathcal{L} –Relation	$\alpha \in$	$Sig(\mathcal{L})$
Expression	$e ::=$	$data(x) \mid data(y) \mid c \mid g(e_1, \dots, e_n)$
AFormula	$\varphi ::=$	$\gamma(e_1, \dots, e_n) \mid \alpha(v_1, \dots, v_n)$ $\mid \neg\varphi \mid \varphi_1 \wedge \varphi_2 \mid \varphi_1 \vee \varphi_2$ $\mid \exists z.\varphi \mid \forall z.\varphi \mid \exists S.\varphi \mid \forall S.\varphi$
\forall Formula	$\omega ::=$	$\varphi \mid \forall y.\omega$
Formula	$\psi ::=$	$\omega \mid \exists x.\psi$

Example: Binary Search Tree



$$\mathit{leftbranch}(y_1, y_2) \equiv \exists z (\mathit{left}(y_1, z) \wedge z \rightarrow^* y_2)$$

$$\mathit{rightbranch}(y_1, y_2) \equiv \exists z (\mathit{right}(y_1, z) \wedge z \rightarrow^* y_2)$$

$$\psi_{bst} \equiv \forall y_1 \forall y_2 ((\mathit{leftbranch}(y_1, y_2) \Rightarrow d(y_2) < d(y_1)) \wedge \\ ((\mathit{rightbranch}(y_1, y_2) \Rightarrow d(y_1) \leq d(y_2))))$$

Example: Two disjoint lists

$(\text{head}_1 \rightarrow^* \text{tail}_1) * (\text{head}_2 \rightarrow^* \text{tail}_2)$ states, in separation logic, that there are two disjoint lists such that one list is from head_1 to tail_1 , and the other is from head_2 to tail_2 .

$$\psi_{2\text{lists}} \equiv \exists \mathcal{S}_1 \exists \mathcal{S}_2 (\text{disjoint}(\mathcal{S}_1, \mathcal{S}_2) \wedge$$

$$\text{head}_1 \in \mathcal{S}_1 \wedge \text{tail}_1 \in \mathcal{S}_1 \wedge \text{head}_2 \in \mathcal{S}_2 \wedge \text{tail}_2 \in \mathcal{S}_2 \wedge$$

$$\forall z. ((\text{head}_1 \rightarrow^* z \wedge z \rightarrow^* \text{tail}_1) \Rightarrow z \in \mathcal{S}_1) \wedge$$

$$\forall z. ((\text{head}_2 \rightarrow^* z \wedge z \rightarrow^* \text{tail}_2) \Rightarrow z \in \mathcal{S}_2) \wedge$$

$$\text{head}_1 \rightarrow^* \text{tail}_1 \wedge \text{head}_2 \rightarrow^* \text{tail}_2)$$

where $\text{disjoint}(\mathcal{S}_1, \mathcal{S}_2)$ is defined as

$$\nexists z (z \in \mathcal{S}_1 \wedge z \in \mathcal{S}_2)$$

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Satisfiability-Preserving Embeddings

- $\exists \vec{x} \forall \vec{y} \varphi(\vec{x}, \vec{y})$ over \mathcal{R} can be transformed to an **equisatisfiable** formula $\forall \vec{x} \forall \vec{y} \varphi'(\vec{x}, \vec{y})$ over \mathcal{R}'

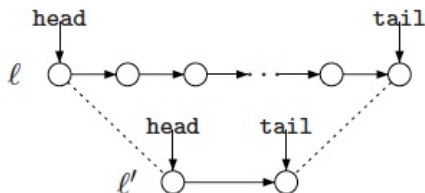
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Satisfiability-Preserving Embeddings

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- Question: How to define the satisfiability-preserving embeddings?
- Needed: if the larger graph model can satisfy φ with some data extension, the smaller model can also satisfy φ with some data extension.

Intuition



- since the data-values in the submodel are **inherited** from the larger model, the atomic data-relations would hold **in the same way** as they do in the larger model
- S **satisfiability-preservingly embeds** in T iff **no matter how** T **satisfies the formula** using some valuation of the atomic data-relations, S will be able to satisfy the formula using the **same valuation of the atomic data-relations**

Observation

STRAND_{dec} : formulas that have a **finite number of minimal models** w.r.t the partial-order defined by satisfiability-preserving embeddings.

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Observation 1: After fixing a particular valuation of \vec{y} , all data-relations γ_i get all fixed

Observation 2: No matter how we choose to evaluate \vec{y} over the nodes of the model, the γ_i relations must evaluate to true or false in such a way that φ holds

Minimal Model

Solution: From $\varphi(\vec{y})$, abstract γ_i as a predicate p_i to get a **pure structural** formula $\widehat{\varphi}(\vec{y}, \vec{p})!$

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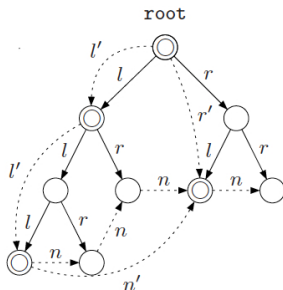
$$\begin{aligned} \text{MinModel} = & \neg \exists X. (\text{ValidSubModel}(X) \wedge \\ & (\forall \vec{y} \forall \vec{p} ((\wedge_{y \in \vec{y}} (y \in X) \wedge \widehat{\varphi}(\vec{y}, \vec{p})) \\ & \Rightarrow \text{tailor}_X(\widehat{\varphi}(\vec{y}, \vec{p})))))) \end{aligned}$$

tailor_X : transform $\widehat{\varphi}$ to a formula that expresses the same property on the submodel defined X .

Decision Procedure

- define the MSO formula on k -ary trees *MinModel* that captures minimal models.
- transform the MSO formula to a tree automaton that accepts precisely those trees that satisfy the formula.
- Since the finite-ness of the language accepted by a tree automaton is decidable, STRAND_{dec} is effectively checkable!

A Decidable Syntactic Fragment of STRAND



\mathcal{R} : Trees **only allow** *LeftSubtree* and *Rightsubtree*

Syntax: $\exists \vec{x} \forall \vec{y} \varphi(\vec{x}, \vec{y})$ where φ is quantifier-free

(for any y_1, y_2 , they are related in T **iff** they are related in *Submodel*(T, S), hence decidable!)

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Program Verification Overview

Hoare-triples: $(\mathcal{R}, Pre, P, Post)$

\mathcal{R}

$Pre \in Strand_{\exists, \forall}$

$P :$

```
Node t = newhead;  
newhead = head;  
head = head.next;  
newhead.next = t;
```

$Post \in Strand_{\exists, \forall}$

\Rightarrow Is $\psi \in Strand$
Satisfiable over \mathcal{R}_P ?

Idea: capture the entire computation P starting from a particular recursive data-structure \mathcal{R} using a single data-structure \mathcal{R}_P

result

$$Error = \bigvee_{i \in [m]} (Pre_{\mathcal{R}_P} \wedge \bigwedge_{j \in [i-1]} \varphi_j \wedge error_i)$$

$$Violate_{Post} = Pre_{\mathcal{R}_P} \wedge \left(\bigwedge_{j \in [m]} \varphi_j \right) \wedge \neg Post_{\mathcal{R}_P}$$

Theorem

The Hoare-triple $(\mathcal{R}, Pre, P, Post)$ does not hold *iff* the STRAND formula $Error \vee Violate_{Post}$ is satisfiable on the trail \mathcal{R}_P .

bst-search-in-loop

bstSearch

(pre: $\psi_{bst} \wedge \exists x. (key(root) = k)$)

Node curr = root;

(loop-inv: $\psi_{bst} \wedge \exists x. (reach(curr, x) \wedge key(curr) = k)$)

```
while (curr.key != k / curr != nil){  
  if (curr.key > k) curr = curr.left;  
  else curr = curr.right;  
}
```

(post: $\psi_{bst} \wedge key(curr) = k$)

Formula

```

macro minimalmodel(var2 $, var1 curr, var1 curr1, var1 exdv1, var1 exdv2, var1 a
notherk, var0 pc1, var0 pc2, var0 pc3, var0 pc4, var0 pc12, var0 pc22) =
  ~ex2 M where M sub $ & M'=$:(
    validmodel'($,curr,curr1,exdv1,exdv2,anotherk,pc1,pc2,M) &
    all1 dv1,dv2,dv3: (
      (dv1 in M & dv2 in M & dv3 in M) =>
      (all0 p11,p21,p3: (
        ((~precondition($,curr,curr1,exdv1,exdv2,anotherk,pc1,pc
2,pc3,pc4,pc12,pc22,dv1,dv2,dv3,p11,p21,p3) | precondition'($,curr,curr1,exdv1,e
xdv2,anotherk,pc1,pc2,pc3,pc4,pc12,pc22,dv1,dv2,dv3,p11,p21,p3,M)) | ~negpostcon
dition($,curr,curr1,exdv1,exdv2,anotherk,pc1,pc2,pc3,pc4,pc12,pc22,dv1,dv2,dv3,p
11,p21,p3)) &
          (~precondition($,curr,curr1,exdv1,exdv2,anotherk,pc1,pc2
,pc3,pc4,pc12,pc22,dv1,dv2,dv3,p11,p21,p3) | (~negpostcondition($,curr,curr1,exd
v1,exdv2,anotherk,pc1,pc2,pc3,pc4,pc12,pc22,dv1,dv2,dv3,p11,p21,p3) | negpostcon
dition'($,curr,curr1,exdv1,exdv2,anotherk,pc1,pc2,pc3,pc4,pc12,pc22,dv1,dv2,dv3,
p11,p21,p3,M)))
      ))));

```

Results of Program Verification

Program	Verification condition	Structural solving (MONA)			Data-constraint Solving (Z3 with QF-LIA)		
		in STRAND ^{dec} ? (finitely-many minimal models)	Time(s)	Graph model exists?	Bound (#Nodes)	Satisfiable?	Time(s)
sorted-list-search	before-loop	Yes	0.34	No	-	-	-
	in-loop	Yes	0.59	No	-	-	-
	after-loop	Yes	0.18	No	-	-	-
sorted-list-insert	before-head	Yes	1.66	Yes	5	No	0.02
	before-loop	Yes	0.38	No	-	-	-
	in-loop	Yes	4.46	No	-	-	-
	after-loop	Yes	13.93	Yes	7	No	0.02
sorted-list-insert-error	before-loop	Yes	0.34	Yes	7	Yes	0.02
	in-loop	Yes	4.41	No	-	-	-
	after-loop	Yes	13.63	Yes	7	No	0.02
sorted-list-reverse	before-loop	Yes	0.24	No	-	-	-
	in-loop	Yes	2.79	No	-	-	-
	after-loop	Yes	0.35	No	-	-	-
bst-search	before-loop	Yes	5.03	No	-	-	-
	in-loop	Yes	32.80	Yes	9	No	0.02
	after-loop	Yes	3.27	No	-	-	-
bst-insert	before-loop	Yes	1.34	No	-	-	-
	in-loop	Yes	9.84	No	-	-	-
	after-loop	Yes	1.76	No	-	-	-

<http://cs.uiuc.edu/~qiu2/strand/>

Future Work

- Powerful and decidable syntactic fragments
- Back-and-forth connection between the structural part and the data part
- Separation logic

Questions?